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OF 25 FOOT TILT ROTOR DURING AUTOROTATION
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WIND TUNNEL TEST RESULTS

OF 25-FOOT TILT ROTOR

DURING AUTOROTATION

REPORT 301-099-005
NASA CONTRACT NAS2-8580







WIND TUNNEL TEST RESULTS OF 25-FT. TILT ROTOR DURING AUTOROTATION

Ву

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By Bell Helicopter Textron

Fort Worth, Texas

For

National Aeronautics and Space Administration

Ames Research Center

Moffett Field, California

This data is furnished in accordance with the provisions of Contract NAS2-8580.



FOREWARD

This report is prepared by Bell Helicopter Textron, Fort Worth, Texas, for the National Aeronautics and Space Administration, Ames Research Center, Moffett Field, California, under Contract NAS2-8580.

The Administrative Contracting Officer was Mr. Dennis Brown. The Technical Monitor was Mr. Kip Edenborough, Tilt Rotor Research Aircraft Project Office. The Tunnel Test Engineer was Mr. Robert H. Stroub, Rotor Group-Large Scale Aerodynamics Branch.

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LIST OF SYMBOLS

	Computer Notation		
Symbol	Scale Data	HSDS	Description
a _{ls}	SAIS	LONSP	Fore and aft flapping angle with respect to the shaft (positive aft), deg
Als	Al	Als	Lateral cyclic angle with respect to the shaft (positive down $\theta = 90^{\circ}$), deg
^b 1 _s	-	LATSP	Lateral flapping angle with respect to the shaft (positive down 0 ψ = 90°), deg
^B 1s	В1	BlS	Fore and aft cyclic angle with respect to the shaft (positive fwd), deg
c	VSND	-	Speed of sound, knots
^С н/σ	CHS	-	H-force coefficient/rotor solidity ratio $C_{H/\sigma} = H/\rho \pi \Omega^2 R^4 \sigma$
C _{L/\sigma}	CLR	-	Lift coefficient/rotor solidity ratio $C_{L/\sigma} = L/\rho \pi \Omega^2 R^4 \sigma$
C _M _X /σ	CMXS	-	Rolling moment coefficient/ rotor solidity ratio $C_{M_X/\sigma} = M_{X/\rho\pi}\Omega^2 R^5 \sigma$
C _M _Y /σ	CMYS	-	Yawing moment coefficient/ rotor solidity ratio $C_{M_{Y}} = M_{Y} / \rho \pi \Omega^{2} R^{5} \sigma$
$C_{M_{Z} \sigma}$	CMZS	-	Pitching moment coefficient/ rotor solidity ratio $C_{M_{Z}/\sigma} = M_{Z}/\rho \pi \Omega^{2} R^{5} \sigma$
C _p	СР	-	Power coefficient based on the mast torque $C_{\rm p} = Q/\rho\pi \Omega^2 R^5$



LIST OF SYMBOLS (Continued)

	Computer No	tation	
Symbol	Scale Data	HSDS	Description
^C p/σ	CPS	-	Power coefficient/rotor solidity $C_{p/\sigma} = Q/\rho \pi \Omega^2 R^5 \sigma$
C _P o σ	CPOS		Minimum power coefficient/ rotor solidity ratio $C_{p_{O} \mid \sigma} = C_{p/\sigma} - (C_{L/\sigma})^{2} \sigma/2^{\mu} - (C_{D/\sigma})^{\mu}$
С _Т	CT	-	Thrust coefficient $C_{T} = T/\rho\pi\Omega^{2}R^{4}$
^C T∕σ	CTS	-	Thrust coefficient/rotor solidity ratio $C_{T/\sigma} = T/\rho \pi \Omega^2 R^4 \sigma$
^C x/σ	CXR	~	Drag coefficient/rotor solidity ratio $C_{X/\sigma} = D/\rho\pi\Omega^2 R^4 \sigma$
^C Υ/σ	CYR	-	Y-force coefficient/rotor solidity ratio $C_{Y/\sigma} = Y/\rho\pi\Omega^2R^4\sigma$
D	D	_	Drag, 1b
D/ σ'	DRG6	-	Drag referred to sea level standard conditions, lb
f	FE	-	Flat plate drag area $F = D/q, ft^2$
FM	FM	-	Figure of merit $FM = .707 C_{T}^{3/2}/C_{p}$
н	FORH	-	H-force, perpendicular to the shaft, lb
H/σ'	FRH6	-	H-force referred to sea level standard conditions



LIST OF SYMBOLS (Continued)

	Computer No	otation	
Symbol	Scale Data	HSDS	Description
HP _{MAST}	МНЪ	-	Horsepower based on mast torque HP = $Q\Omega/550$
HP _{MAST/σ} '	PWR6	-	Horsepower based on mast torque referred to sea level standard conditions.
нРв	нрв	-	Horsepower based on wind tunnel balance
HPLC	PLC	-	Horsepower b a sed on test stand load cell
L	L	_	Lift, 1b
$^{ m L/}\sigma'$	LFT6	-	Lift referred to sea level standard conditions, lb
MTIP	MTIP	-	Advancing tip Mach number $M_{\text{TIP}} = (V_{\text{FPS}}^2 + (\Omega R)^2 + 2V_{\text{FPS}}^2 \Omega R \cos \alpha_s)^{1/2} / c$
	PT	-	Data point number
đ	Q	-	Dynamic pressure, lb/ft ²
Q _{MAST}	SFTQ	MASTQ	Mast torque, ft-lb
Q _{LC}	QLC	QLC	Load cell torque, ft-lb
R	R	-	Rotor radius, ft
Т	THST	_	Thrust along the shaft axis, lb
Τ/σ'	тѕт6	-	Thrust referred to sea level standard conditions, lb
V _{KTS}	VKTS	-	Tunnel speed, knots
V _{TIP}	OR	-	Rotor tip speed, $V_{ exttt{TIP}} = \Omega^R$, ft/sec
Y	SIDE	-	Y-force, 1b
Υ/σ'	SID6	-	Y-force referred to sea level standard conditions, lb



LIST OF SYMBOLS (Continued)

	Computer No	otation			
Symbol	Scale Data	HSDS	Description		
α _C	ALFC	-	Control axis angle of attack, $\begin{array}{ccc} \text{deg} & \alpha_{\text{c}} = \alpha_{\text{s}} - B_{1_{\text{S}}} \end{array}$		
ας	ALFS	-	Shaft angle of attack referred to wind axis, deg		
α _{TTP}	ALTP	-	Tip path plane angle of attack, $deg \qquad \alpha_{TTP} = \alpha_{S} - 90 + a_{1_{S}}$		
η	EFF	-	Propulsive efficiency based on the mast torque power $\eta = (\text{T V}_{\text{FPS}}) \cos \alpha_{\text{S}}/550 \text{ HP}_{\text{MAST}}$		
$\theta_{ ext{TIP}}$	ТНТА	THETA	Tip collective angle, deg		
μ	ADVR	-	Advance ratio $\mu = V/\Omega R$		
Ω	RPM	NPR	Rotor rpm, rpm		
σ	SlG	-	Rotor solidity (.0891)		
σ'	RHOR	-	Air density ratio $\sigma' = \rho/\rho_0$		



I. SUMMARY

A 25-foot diameter tilt rotor was tested in the NASA-Ames 40- by 80-foot Large-Scale Wind Tunnel under NASA Contract NAS2-8580. The test confirmed the predicted autorotation capability of the XV-15 tilt rotor aircraft.

Autorotations were made at 60, 80, and 100 knots. A limited evaluation of lateral cyclic was made. Due to instrumentation, electrical, and mechanical problems, there was not time to expand the 1970 test envelope. Check runs that were made compared with the 1970 wind tunnel test at hover and 80 knots.

Test data indicate a minimum rate of descent of 2200 feet per minute at 60 knots at the XV-15 design gross weight of 13,000 pounds.



6

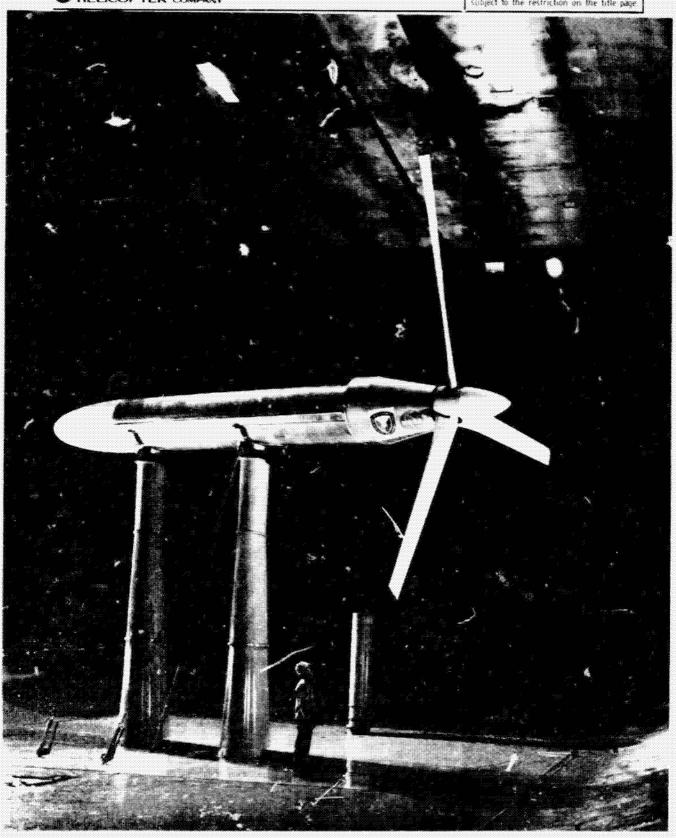
II. INTRODUCTION

This report presents the results and a brief analysis of a wind tunnel test of a 25-foot-diameter rotor designed for tilt-rotor aircraft operation as shown in Figure II-1. Testing was accomplished to determine rotor performance and blade loads during forward flight and autorotation. The rotor tested was identical to that used on the XV-15 tilt rotor research aircraft. Testing was accomplished in the NASA-Ames 40- by 80-foot wind tunnel. Work to prepare the model, testing, and documentation were accomplished under NASA Contract NAS2-8580.

This particular rotor configuration was tested in the ARC 40-by 80-foot wind tunnel in 1970 to obtain performance, blade loads, and dynamic stability characteristics in forward flight. Since that time, the control system design of the rotor has been changed to incorporate provisions for lateral cyclic control. In addition, the autorotation capabilities of the tilt rotor have been given considerable attention since that testing through analytical work and small scale model tests. The indications were that autorotation would be a critical area of operation and require full scale testing. Since the 1970 test, the tunnel test stand configuration was changed to accommodate autorotation shaft angles allowing the expansion of the test envelope of the tilt rotor.

Several instrumentation problems encountered during this test, although unrelated to rotor performance, limited the forward flight testing. Limited testing was accomplished to verify the effects of lateral cyclic on the reduction of lateral flapping and blade loads. Most of the test period was spent obtaining autorotation characteristics at several shaft angles and airspeeds. Comparisons made between analytical methods and test show the rotor to require higher shaft angles to autorotate than predicted.





II-1. 25-Foot Tilt Rotor/PTR in NASA-Ames 40- by 80-Foot Wind Tunnel



III. DESCRIPTION OF TEST HARDWARE

A. Tilt Roter and Controls

1. Description

The 25-foot three-bladed tilt rotor is a gimbaled, stiff-inplane rotor with an elastomeric hub spring to provide increased control power and damping during helicopter mode. The rotor has a swashplate which provides two axes of cyclic pitch and has positive pitch flap cou; ing. Blade collective pitch is provided by a rise-and-fall collective head assembly above the rotor through three walking beams. Rotation of the rotors is such that inboard blade tip rotation is aft for helicopter mast angles and up for airplane mast angles. During this test the right hand rotor was tested giving rotation clockwise (view looking forward).

The blades have a bonded aluminum honeycomb afterbody and 17--7PH stainless steel spars and skins. The airfoil sections vary from an NACA 64--208 section at the tip to a NACA 64--429 at the root (r/R=.15). The combination of twist and camber was selected to meet the aerodynamic requirements for both helicopter and airplane flight, and to permit the blade spar structure to have a uniform twist rate. Total aerodynamic twist from rotor centerline to blade tip is 45 degrees.

Table III-1 provides a summary of the pertinent data concerning the rotor. References 1 and 2 provide a complete description of the rotor

2. Natural Frequencies

Prior to the wind tunnel tests, the rotor natural frequencies were calculated using the Myklestad - BHT normal modes program. These results were then compared with the frequencies reported in reference 2.

Figure III-l shows the results obtained for the asymmetric (cyclic) modes, while Figure III-2 gives the comparison for the symmetric (collective) modes. These figures show good agreement between the recently calculated frequencies and those previously reported, especially for the lower frequencies.



The fan plots indicate that there would not be any serious resonance problems at operating RPM. During the test, the small resonance at 350 RPM, during run up to rpm, was quite evident confirming the crossing of the 2/rev line by the first cyclic inplane mode. Other than that, no problems were encountered.

B. Test Stand

1. Description

Test stand used for this test was the NASA Propeller Test Rig (PTR). The power module of this test rig consists of two 1500-HP electric motors mounted in tandem on a frame, driving an R-2800 engine reduction gearbox. The power module was mounted on the two 15-1t. main struts to the balance frame in the 40- by 80-foot wind tunnel. With the PTR in this configuration, rotor shaft angle-of-attack was changed by yawing the complete test rig. At $\psi = 0^{\circ}$, the rotor was in airplane flight. At $\psi = 90^{\circ}$, the rotor was in helicopter flight. Shaft angle-of-attack range tested was from 0 degrees (airplane) to 110 degrees (helicopter-autorotation). Tunnel test stand has the capability of varying shaft angle from +109 to -191 degrees.

The rotor gearbox adapter and mast case to the PTR was the same as used during the 1970 wind tunnel test as described in Reference 1.

2. Natural Frequencies

A vibration analysis of the Propeller Test Rig, with the 25-foot tilt rotor installed, was made prior to testing. The test stand structure was modeled on the NASTRAN structural analysis and the natural frequencies determined as reported in the pre-test report, Reference 3.

A vibration survey of the actual Propeller Test Rig installed in the tunnel was made without a rotor to determine the principal frequencies and damping of the structure and with dummy weights representative of the rotor. The rotor-off transfer function was measured in the longitudinal, lateral, and vertical directions for yaw angles of $\psi = 0^{\circ}$ and 90° . Rotor weights-on results were obtained for lateral and vertical modes at $\psi = 0^{\circ}$ only. The direction of shaking (lateral or longitudinal) is defined with respect to the PTR module, not the halance and wind tunnel. The test procedure and complete results are described in detail in References 4 through 6.

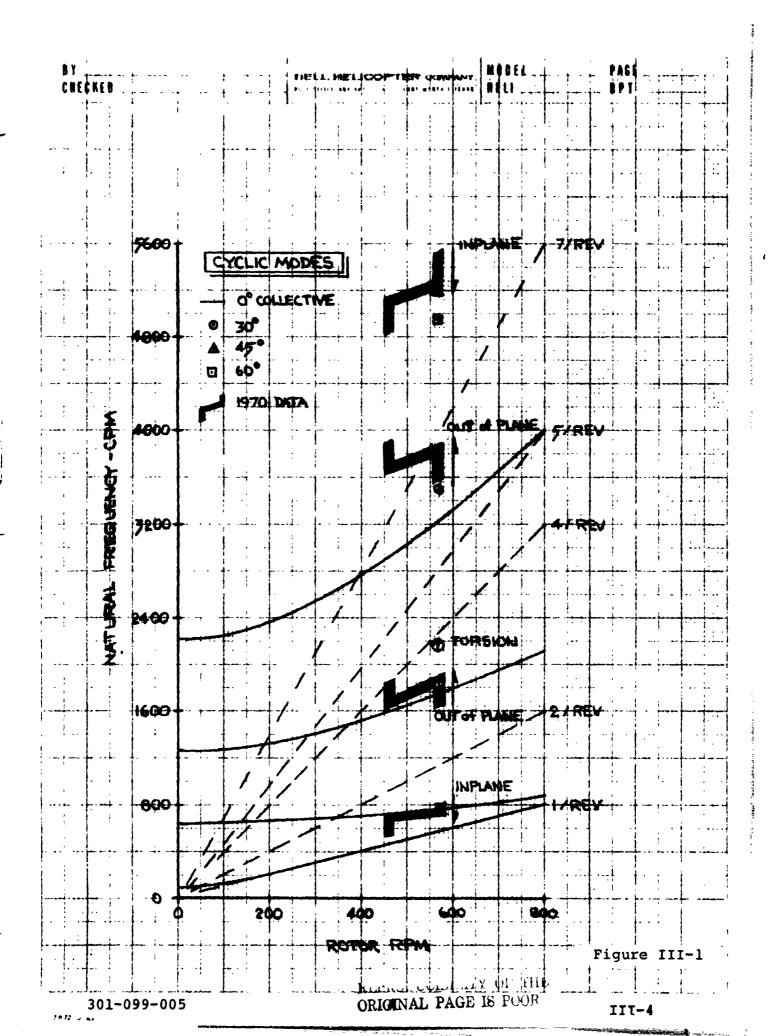


The measured test stand natural frequencies are compared to the calculated frequencies in Table III-2.

C. Instrumentation

Conventional instrumentation was used to measure loads, control positions, deflections, and accelerations. Rotating system instrumentation channels utilized a 52-ring slipring to provide 2 excitation power channels and 24 data channels. Table III-3 summarizes the data channels recorded. All channels were recorded on the 40- by 80-foot wind tunnel High Speed Data Acquisition System (HSDAS). The HSDAS was used to provide digital printouts of analog traces, harmonic analysis, and calibration information. One oscillograph was used to monitor critical items during the test. The 50-channel Peak to Peak indicator unit was also used to monitor loads and vibration levels of all channels during the test. Yoke and blade beam /chord (Sta. 8.4 and 52.5) loads along with pitch link oscillatory loads were monitored on an oscilloscope and on the model control console panel.

⁽¹⁾ Originally only one excitation power channel and 25 data channels were available. High line voltage drop between the model and recording systems and the loss of one data channel allowed changing to two power channels. This change reduced the line voltage drop to a more acceptable level.



CIENTEN C. 1875



TABLE III-1. ROTOR DESCRIPTIVE DATA

 	
Number of blades	3
Diameter	7.62m (25 ft.)
Disc Area	45.6m ² (491 ft. ²)
Blade Chord	.356m (14 in.) (17 in. @ .0875R tapering to 14 in. at .25R
Blade Area (Total 3 blades)	4.06m ² (43.75 ft. ²)
Solidity	.089
Blade Airfoil Section Root (C _L mast) .15R .25R .50R .75R 1.00R	NACA 64-935 NACA 64-429 NACA 64-425 NACA 64-218 NACA 64-112 NACA 64-208
Blade Twist Aerodynamic Geometric Hub Precone	45 deg 40.9 deg
	2.5 deg
δ ₃	-15.0 deg
Hub Spring	2700 in-lb/deg
Flapping Design Clearance	[±] 12/0 deg
Blade Inertia (per blade)	102.5 slug-ft ²
Rotor rpm/tip speed Helicopter Airplane	565 rpm/740 ft/sec 458 rpm/600 ft/sec



TABLE III-2. PROPELLER TEST STAND NATURAL FREQUENCIES

	Measured - HZ			NASTRAN
Mode	Roto	or-Off	Rotor-On	Model
			(equiv wt.)	(equiv. wt.)
	Ψ=0°	ψ ≈90	$\psi = 0^{\circ}$	
Lateral Modes				
Balance Lateral	1.73	1.29	1.65	1.43
Yaw	3.14	2.41	3.26	2.09
Strut Side	5.56	5.55	4.90	6.68/2.52
Module	12.3	11.7		
Module	17.2	15.9		16.9
Mast			20.4	21.6
Module	33.3	33.1		
Longitudinal Modes Balance Longitudinal Strut Longitudinal Module Module Vertical Modes	1.44 3.54 16.2 28.6	2.3 3.9 16.8 28.8		1.80 3.99 20.24
Balance Balance Balance Balance Module Module Mast		1.56 2.31 5.54 7.64 13.5 16.4	7.34 11.0 14.7 24.0	7.90 12.8 14.45 29.03



TABLE III-3. INSTRUMENTATION

Item	Chann HSDAS	el No. O-Graph	Computer Notation
Plade heaving herding manage	1		
Blade beamwise bending moment -Sta. 22.825 (red blade)	1		BB23
Blade beamwise bending moment -Sta. 52.5 (red blade)	2	3	BB53
Blade beamwise bending moment -Sta. 75.0 (red blade)	3		вв75
Blade beamwise bending moment -Sta. 112.5 (red blade)	4		BB113
Blade chordwise bending moment -Sta. 52.5 (red blade)	5	8	CH53
Blade chordwise bending moment -Sta. 75.0 (red blade)	6		CH75
Blade chordwise bending moment -Sta. 112.5 (red blade)	7		CH113
Blade torsion - Sta. 52.5 (red blade)	8		TR53
Blade torsion - Sta. 112.5 (red blade)	9		TR113
Blade stress trailing edge -Sta. 75.0	10		TE 75
Blade stress leading edge -Sta. 9.5	11	20	LE9
Blade stress trailing edge -Sta. 9.5	12	21	TE9
Yoke chordwise bending moment -Sta. 8.375 (red blade)	13	23	YOKEC
Yoke beamwise bending moment -Sta. 8.375 (red blade)	14	24	YOKEB



TABLE III-3. (Continued)

	Channel No.		Computer
Item	HSDAS	O-Graph	Computer Notation
Fork stress (red blade)	15		FORK2
Fork stress (white blade)	16		FORK1
Mast perpendicular bending	17	26	MPERP
Mast parallel bending	18	5	MPARA
Mast torque	19	9	MASTQ
Pitch link axial load (red blade)	20	27	PLINK
Blade feathering (red blade)	21		PITCH
Blade flapping (red blade)	22	32	FLAP
Swashplate driver load	23	33	SDRIV
Collective slider - parallel bending	24		CSPAB
Collective slider - perpendicu- lar bending	25		CSPEB
Lateral flapping	26		LATSP
Fore and aft flapping	27		LONSP
Collective tube axial load	28	13	COLAX
Lateral cyclic tube axial load	29	17	LATAX
Longitudinal cyclic tube axial load	30	29	LONAX
Collective position	31		THETA
Lateral cyclic position	32		Als
Longitudinal cyclic position	33		BlS
Mast case vertical acceleration (reference to helicopter $\psi=0$)	34		ACCV



TABLE III-3. (Continued)

Item	Chan HSDAS	nel No. O-Graph	Computer Notation
Mast case lateral acceleration (reference to helicopter $\psi = 0$)	35		ACCLA
Mast case fore/aft acceleration (reference to helicopter ψ = 0)	36		ACCLO
Forward strut lateral accelera- tion	37		SAFLA
Aft strut lateral acceleration	38		SAALA
Strut longitudinal acceleration	39		SALO
Torque-transmission load cell	40		QLC
Static pressure	41		PSTAT
Lateral displacement guage-fwd	42		FLADG
Lateral displacement guage-aft	43		ALADG
Twice longitudinal flapping	44		LODG



IV. DESCRIPTION OF TEST

Testing was accomplished in the NASA-Ames 40- by 80-foot wind tunnel during 8 November 1975 through 23 November 1975 and designated Test No. 472. The test was to evaluate tilt rotor autorotation characteristics, the effect of lateral cyclic on rotor flapping and blade loads, and to expand the 1970 wind tunnel test envelope. Total occupancy time was 165 hours (blades on ready for track and balance). Instrumentation and mechanical problems accounted for most of the occupancy time leaving 11.5 hours of rotor on testing. A total of 128 points was obtained during this period for a 6.9 percent utilization of available test time.

Force and moment data was measured by the wind tunnel balance and converted to rotor thrust, H-force, Y-force, and torque. A second method used to measure torque was from a load cell on the test stand. The primary torque measurement was from a strain-gage on the rotor mast. The power coefficients and data presented in this report use the mast torque strain-gage because it was found to be more accurate than the other two methods. (The other two measurements were dropped from the scale data output. Power measurement by these methods appeared unreasonable and would not correlate with most torque measurements.) In addition, rotor rpm, collective pitch, cyclic pitch, and flapping angles were measured. For a more detailed description of data measured, rotor instrument and force/angle relationships, see List of Symbols, Section III.C, and in Section V respectively.

The major test variables were tunnel speed and shaft angle, see Run Schedule in Appendix. Generally, during the runs collective pitch was varied while other variables were held approximately constant. Fore and aft cyclic pitch was adjusted to hold fore and aft flapping constant at zero. Lateral cyclic pitch was set to zero during most of the test, but was changed to -4.0 degrees to obtain the effect of lateral cyclic on blade loads.

Basic procedure for the start of each run was to set the controls to zero ($\theta_{\text{TIP}} = B_1 = A_1 = 0^{\circ}$), bring the rotor to the desired rpm, then bring the tunnel up to speed. As tunnel speed increased, fore and aft cyclic pitch was changed to hold flapping to zero. Once the tunnel was on the desired test speed, collective sweeps were made so as not to exceed blade endurance limits. During the autorotation runs, the same initial start-up procedure was followed with the shaft angle set at 90 degrees while tunnel speed was increasing to the test speed. As shaft angle was increased for autorotation, collec-



tive pitch was reduced to keep from stalling the rotor. At the specified shaft angle, collective sweeps were made from the lower limit ($\theta_{\rm TIP} = -8^{\rm O}$) to a setting above the bucket in the thrust/power curve (generally $\theta_{\rm TIP} = 0^{\rm O}$).



V. DATA REDUCTION

Force and moment data, measured on the wind tunnel balance were reduced using a NASA-Ames data reduction program for scale data. Control positions and test conditions were thumb wheeled in for reference. Test a ta computer notation for the scale data is given in the List of Symbols for comparison with the symbol as used in this report. The force and moment sign convention used during this test is shown in Figure A-1. Scale data is given in the Appendix.

Rotor loads, stress, accelerations, and control positions were recorded on the High-Speed-Data-Acquisition System. Computer notation, channel number reference, and channel description is given in Table III-3, Section III. Due to the bulk of this information, the HSDAS information is not presented. The major test parameters recorded from this system that are presented in this report are tabulated (collective pitch, cyclic pitch, flapping, blade loads) in the Appendix.

Tare runs were made after the test. The only item modified on the model was the nonrotating fairing of PTR. It was interferring with the swashplate driver and had to be cut back past the rotating parts (approximately a 6.0 inch gap between the fairing and spinner). This did not seem to change the tare data significantly when compared with the previous tare from the 1970 test. Figures V-1 and V-2 compare the spinner tare used during the 1970 test with that of this test.

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VI. RESULTS OF TEST

Test results are divided into three sections, hover performance, forward flight, and autorotation. The first two configurations were tested to establish a correlation with the 1970 test. Autorotation data was made available as the result of this test. Therefore, comparisons are made between this test and the 1970 test for hover and forward flight and between this test and estimates for autorotation.

A. Hover Performance

Figures VI-1 and VI-2 present a summary of hover testing performed on the 25-foot rotor. Most of the hover testing in the wind tunnel was with the shaft angle at zero degrees (pointing upstream in the tunnel). In this configuration, the rotor produces enough circulation in the tunnel to develop airspeeds up to 20 knots for a low speed axial flight configuration. As the shaft is tilted towards helicopter, hover performance was shown to improve.

Figure VI-3 compares the test hover performance (whirl test) with the calculated from tilt rotor simulation (IFHB75), F-35, and C-81 computer programs. The math model representation for the IFHB75 rotor is a closed solution of the rotor disk whereas, C-81 determines rotor characteristics for twenty blade elements for several azimuth positions and uses two dimensional airfoil sectional data for five radial stations. Induced velocity distribution tables were used to give an elliptical distribution as opposed to conventional triangular distribution. With this type of distribution, good correlation is obtained between computed and test.

B. Forward Flight

Only one forward flight condition was obtained for comparison with the 1970 test. This case was for a shaft angle of 75 degrees at 80 knots. Comparison of rotor characteristics is shown in Figures VI-4 through VI-9.

Correlation between the two test results was good. High collective pitch testing was limited because of instrumentation problems in measuring blade loads and incidences of loosing rotor control at electrical connections to the control actuators. Data obtained was sufficient to establish that the rotor characteristics were similar to the last test and pre-test predictions.



C. Autorotation

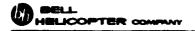
Autorotation capability of the tilt rotor was investigated at 60, 80, and 100 knots for several shaft angles. Most of the autorotation data was taken at 458 rpm (600 fps). This is airplane mode cruise rpm. Analysis and simulation tests have shown this to be a more realistic autorotation rpm as opposed to the pre-test selected 565 rpm. A limited amount of testing was at 535 rpm which shows that autorotation capability tends to decrease with increasing rpm. Since pre-test estimates were for 565 rpm, post test comparisons are shown using IFHB75 and C81 calculations at 458 rpm which were made after the test.

Figures VI-10 through VI-12 compare the test data with IFHB75 calculations for 60, 80, and 100 knots. The computed autorotation is shown to be optimistic, i.e. less shaft angle required to autorotate. The differences become larger with increasing airspeed. Maximum thrust correlation between calculated and test is good. These two effects limit the airspeed range for autorotation. Wing loading during autorotation needs to be considered to unload the rotor to keep from stalling the rotor. Maximum thrust of the rotor at 458 rpm is between 4900 and 4400 pounds for 60 and 100 knots respectively.

Figure VI-13 compares the test data with C-81 calculations at 80 knots. The computed autorotation in this case is shown to be slightly conservative. Shaping of the thrust-power variation is closer than computed by the more linear IFHB75 rotor equations. Again the maximum thrust limit comparison is good.

Figure VI-14 is a comparison of fore/aft cyclic control position and lateral flapping. Fore/aft cyclic calculated by IFHB75 is less than that computed by C-81 and the test values. Both methods compute lower lateral flapping than test. This indicates the fore and aft induced velocity distribution to be highly nonlinear. Indications show it to be more so during autorotation than forward flight. This is based on that comparisons made in forward flight have shown better agreement for lateral flapping toward substantiating the distribution used.

Blade loads were low and comparable to calculated as shown in Figure VI-15. The variation of loads with collective pitch and shaft angle show the test values to be relatively constant. The effect of lateral cyclic on blade beam bending moment is shown in Figure VI-16.



Rotor performance parameters of power and lift coefficients during autorotation are presented in Figures VI-17 through VI-19 for 60, 80, and 100 knots respectively. The C parameter is used as an indicator of rotor stall. The calculated values from IFHB75 and C-81 are compared with test in Figure VI-18. The C-81 rotor shows better agreement than the IFHB75 rotor. Figure VI-20 summarizes the projected maximum $C_{\text{L}/\sigma}$ for forward flight and autorotation configurations tested at $^{\pm}15$ degrees shaft angles from vertical.

Figure VI-21 summarizes the autorotation rate of descent capabilities computed for the XV-15 which includes the contribution of the airframe for a gross weight of 13,000 The optimum rate of descent was found to be obtained by tilting the nacelles to 95 degrees and positioning the flaps at 40 degees. Rate of descent can be held to around 2400 fpm if proper aircraft attitude and collective pitch are maintained. These results are different than observed during previous tilt rotor simulation tests for the XV-15. During the simulation tests, autorotation was made with the collective pitch set on the lower limits at -7.5 This requires the rotor to autorotate on the back side of the thrust/power bucket. Thrust provided by the rotor is lower and in order to trim the aircraft, the wing is operating very near maximum lift. This combination results in higher sink rates. Autorotation test results show that the optimum collective pitch setting for the tilt rotor to be about -5.0 degrees, which allows the rotor to operate on the front side of the thrust/power This increases the thrust provided by the rotor and reduces the lift required by the airframe.

As shown in the previous figures, the shaft angle required from test was greater than calculated. Autorotation at shaft angles around 105 degrees and with the nacelles at 90 degrees would generally require flying beyond wing stall. Tilting the nacelles to 95 degrees reduces the wing angle of attack and rate of descent. Raising the flaps would tend to stall out the rotor at low rpm or require higher rpm for autorotation resulting in higher sink rates and reduced flare capability. Equations used to estimate the autorotation rate of descent shown in Figure VI-21 and a sample calculation is given below.



Autorotation rates of descent were calculated using the following simplified method to account for the airframe.

$$R/D = V_{FPS} \sin \gamma$$
where
$$\gamma = \tan^{-1} (\frac{D^{rag}}{Lift})$$
 $Lift = T_{ROTOR} \sin \alpha_S + L_{AIRFRAME}$
 $D^{rag} = T_{ROTOR} \cos \alpha_S + D_{AIRFRAME}$

$$\alpha_S = \alpha_F + i_N$$

Thrust of the rotor is obtained from Figures VI-10 through VI-12 at shaft angles for HP = 0 and HP = -20 (accounting for accessory and transmission drive). Lift and drag of the airframe are obtained from Reference 7.

For V = 80 kts,
$$i_N = 95^{\circ}$$
, $\delta_F = 40^{\circ}$, HP = -20, $\alpha_S = 107^{\circ}$
and $\theta_{TIP} = -5^{\circ}$
 $T_{ROTOR} = (3450)(2) = 6900$ pounds
 $\alpha_F = 105 - 95 = 10$ deg
Lift = 6900 sin 107 + 1.32 (21.69)(181)⁽¹⁾ + 1000⁽¹⁾=12780
Drag =-6900 cos 107 + .45 (21.69)(181)⁽¹⁾ + 150⁽¹⁾=3934
 $\therefore \gamma = \tan^{-1} (\frac{3934}{12780}) = 17.1$ degrees
R/D = 101.26(80) sin 17.1 = 2383 fpm

$$^{(1)}C_{L_{WING}}$$
 @ α_{F} = 10 deg = 1.32
 $C_{D_{WING}}$ @ α_{F} = 10 deg = .45

1000 pounds approximate lift of fuselage and empennage. 150 pounds approximate drag of fuselage and empennage.



Rate of descent for autorotation was determined for the optimum collective pitch and shaft angle to trim the aircraft at 458 rpm (600 fps) and 13000 pounds. At a specific collective pitch angle, rpm and shaft angle would change for a trim condition. The rates of descent for the collective pitch set on the lower limit ($\theta_{\rm TIP} = -8.0$ degrees) is also presented. These values may not be the same as the actual aircraft operating at different gross weight, rpm, or collective pitch settings. This is likewise the case for the simulation test results which was at a lower rpm.

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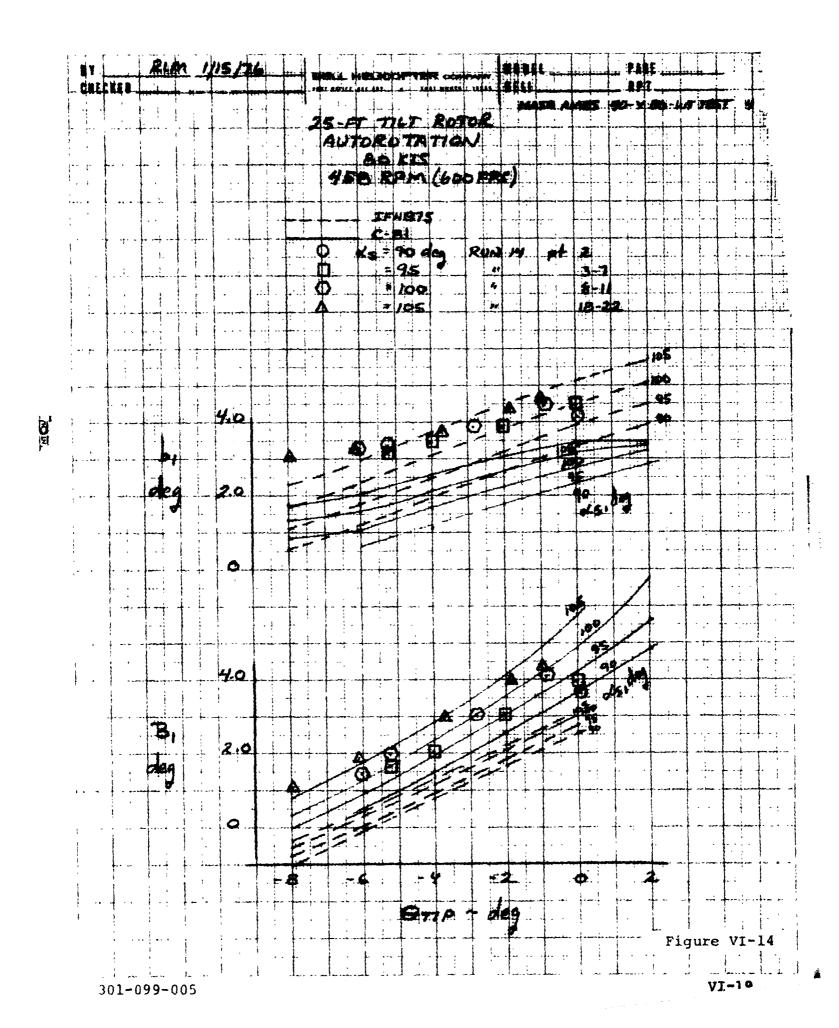
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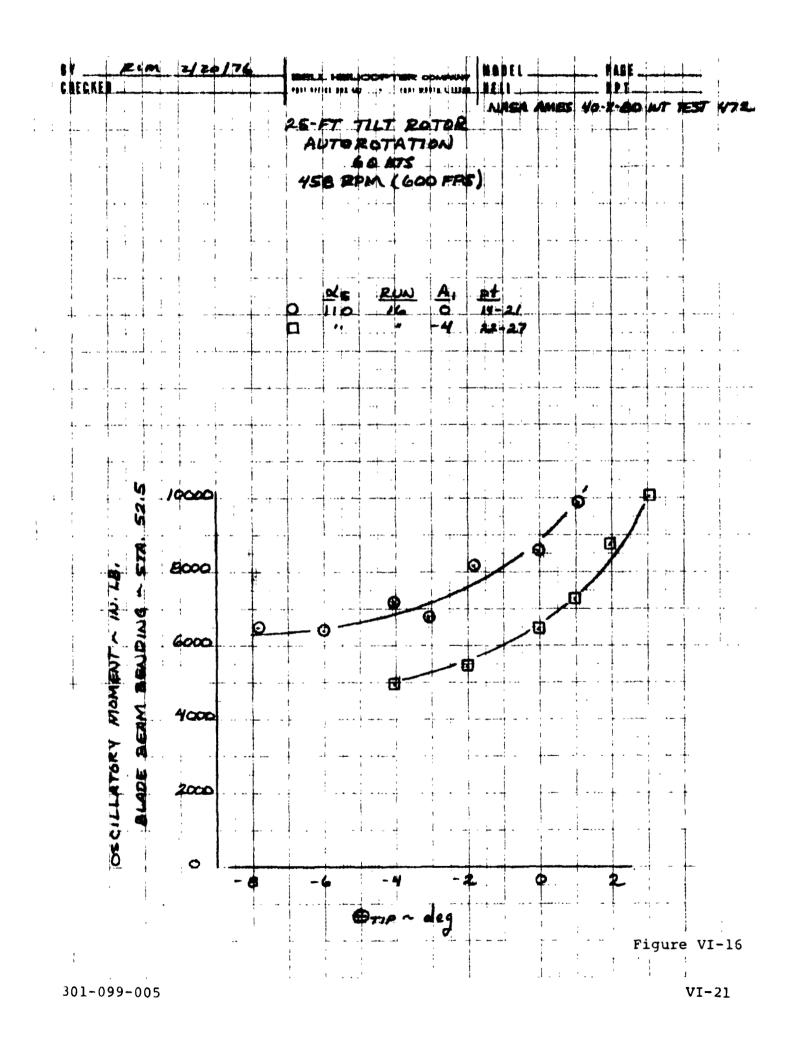
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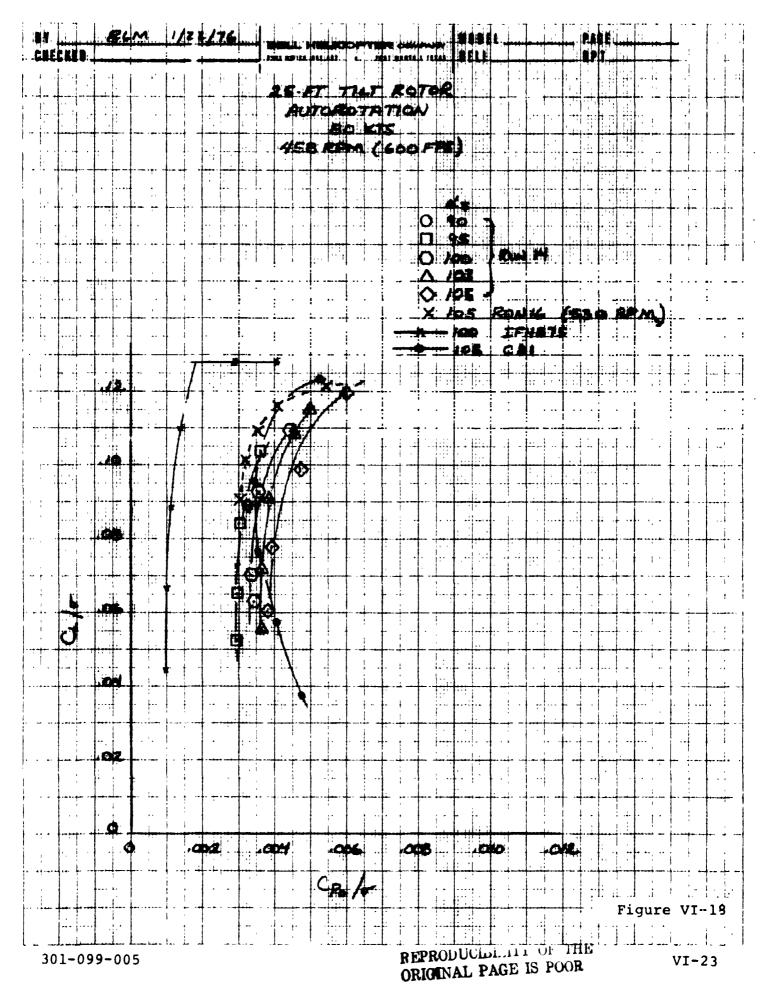
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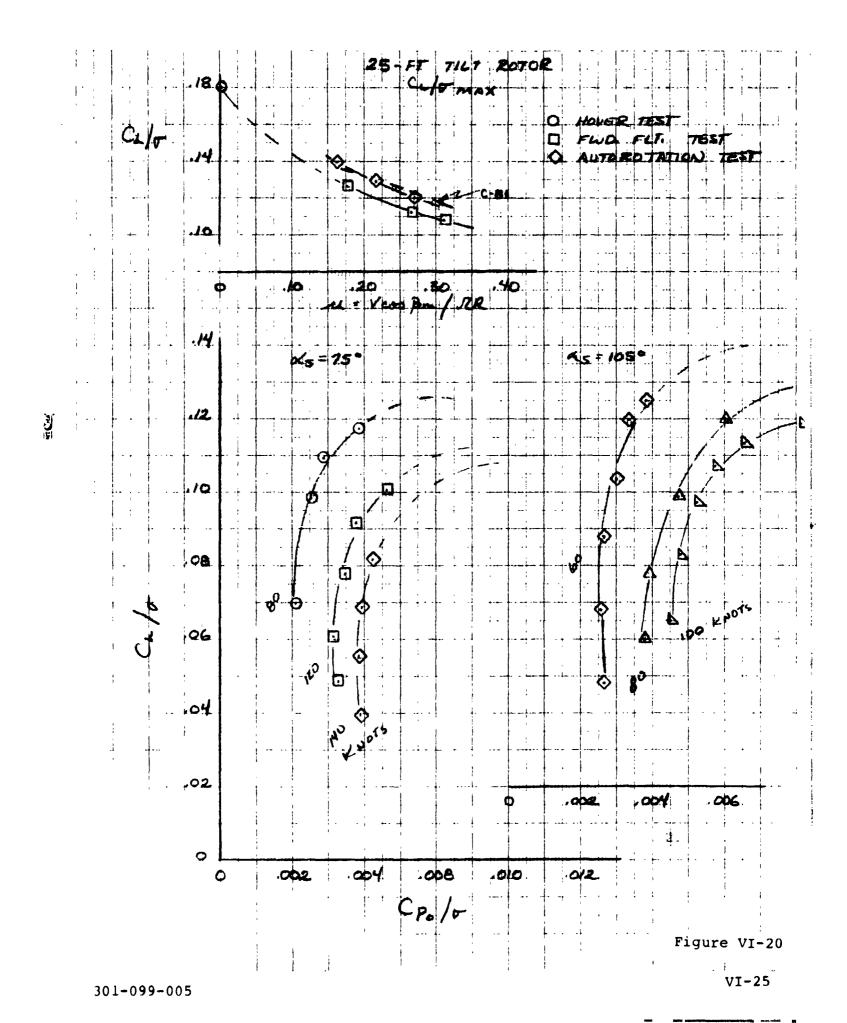
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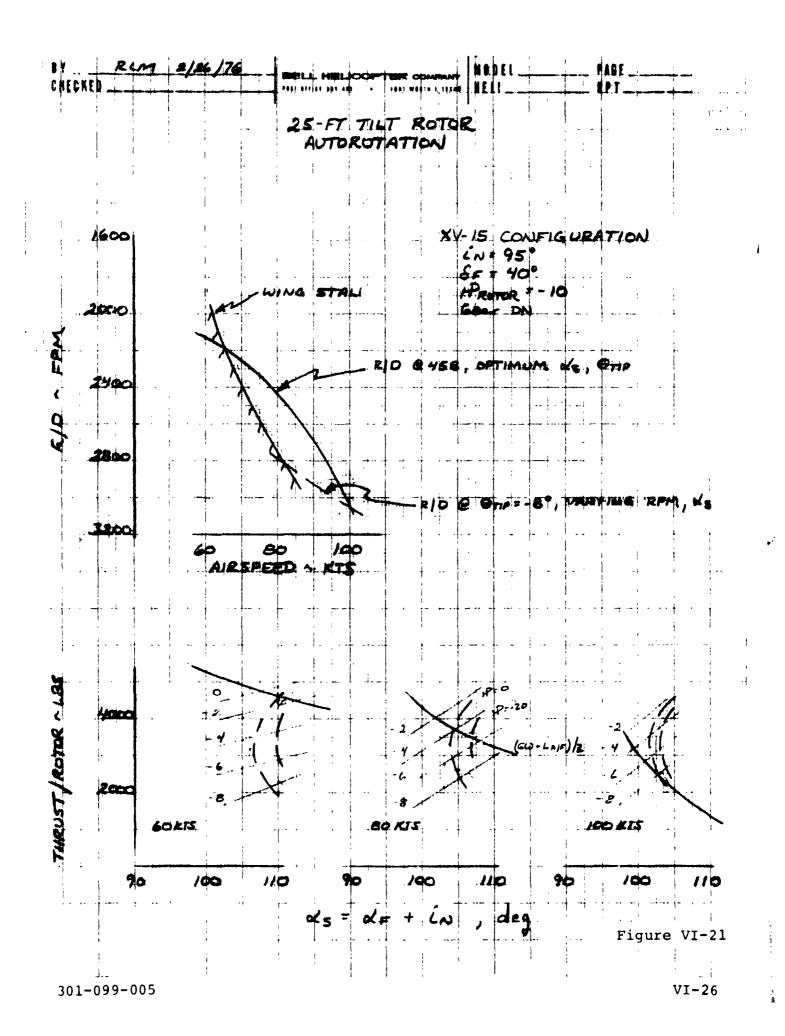


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VII. CONCLUSIONS AND RECOMMENDATIONS

Although all test objectives were not accomplished, autorotation capability of the tilt rotor was confirmed. Autorotation capability was shown for variations in airspeed and rpm. Limited analysis indicates that the autorotation rates of descent of the XV-15 will be similar to predicted and that demonstrated during the tilt rotor simulation tests, but the shaft angles required would be approximately 5 degrees greater than pretest predictions. Use of lateral cyclic to reduce lateral rlapping and blade loads was Rotor characteristics were similar to predicted, but indications are refinements need to be made to the drag representation in the rotor math models at low collective pitch settings before additional analysis is made. recommended that the rotor math model for the tilt rotor simulation be improved to better represent the tilt rotor autorotation characteristics for analysis of the optimum autorotation configuration, i.e. nacelle incidence, flap setting, rpm, collective setting, and airspeed.

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TEST INSTRUMENTATION PROBLEMS

Several instrumentation problems were encountered during the 25-foot powered test at NASA-Ames 40- by 80-Foot Wind Tunnel during November 1975. It was felt that a discussion of these problems and possible ways that they can be avoided on future tests be included in this report. Table A-2 summarizes the problems encountered during the test. These problems generally fall into six (6) categories as follows:

I. Centrifugal Force on Connectors

Connectors were placed in the rotating system to expedite any test part replacement. As the test was run, the centrifugal force on their mass caused strain on the wire, and eventually caused wire failure. When the cause of these failures became evident, the connectors were removed and the wires were spliced together. In the future, connectors will be used only at location where they can be bonded (rotor blades, hub, etc.) or tied securely and taped (pitch links, cyclic tubes, etc.).

II. Centrifugal Force on Wire Loops

Since the slip ring wires must be routed out of the hub assembly to the top of the collective head, a loop of wires was formed. This loop was necessary due to the motion of the collective head with respect to the hub assembly as blade pitch was increased and decreased. Centrifugal force on this loop caused broken wires on several occasions due to fatigue. One solution for this problem would be to route a strain relief wire along with the bundle to take this strain away from the signal wires. A program to test the effects of centrifugal force might need to be initiated to determine proper strain relief techniques on wires. Another possible solution to this problem could be a redesign of the collective head (like the XV-15 flight hardware). This would allow the use of the flight test slip ring assembly and would eliminate the loop completely as the wires would be routed inside the collective tube to the slip ring.

The slip ring would be mounted on the top of the collective head, not below the swashplate as it was during this model test.

III. Motion Between Model and Cowling

A new drive motor stand was used for this test. Between the motor stand and the outer cowling existed a possible ± 2.5 inches

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of motion. To provide mechanical clearances, the front 6 inches were trimmed from the outer cowling. For ease of access, the instrumentation J-boxes were mounted on the cowling, not on the model. The vibration levels on this outer cowling were very high and the wind turbulence inside the cowling (with the forward portion cut off) was also high. The model-to-cowling motion, the cowling vibration and the wind turbulence each contributed to cause many broken wires due to fatigue. Possible solutions to these problems are: mounting of the J-boxes on the model where a more stable mount can be made; making a better nose cowling to reduce wind turbulence inside the nose cowling; improved cable routing and better securing techniques to control cable motion (eliminating fatigue points); larger gage wire for better fatique characteristics.

IV. Slip Ring Wire Routing

The slip ring system for this model has been a source of trouble during all tests on which it has been used. The slip ring itself is not the problem. The problem is the means by which the wires must be routed from the slip ring to the rotating system. All 52 wires must pass through two 1-inch holes after being fanned through the teeth of the mast splines. This is necessary since the wires must pass under the nonrotating section (hub spring) of the rotor assembly. Due to this design, there is no solution to this problem except those solutions discussed earlier (use of flight slip ring with redesign of collective head; strain relief wires).

V. Short Calibration Steps

During the checkout of the instrumentation following installation in the tunnel, two channels were found to have short calibration steps. The short calibration steps caused the loads data to be incorrect at these two locations. After much checking, by both NASA and BHT personnel, the problem was found to be two pins shorted in one of the NASA connectors under the tunnel floor. This short had not shown up in previous tests because of the six wire system that the NASA tunnel uses. For this test a common power supply was used due to the limited amount of rings in the slip ring. Once the short was cleared, a check calibration of the system, using known weights at a given station, proved the data to be correct.

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VI. Random 60 Hz Noise

During the entire test, the rotating channels were plagued by random 60 Hz noise. Many checks and many attempts were made to find the source and a cure for the problem, but none was found. It is now thought that the interface of the common bridge voltage for the rotating channels with the tunnel signal conditioning was the sole or major cause of the problem. For any future tests using this common bridge voltage, a test setup should be made to allow inserting dummy bridges into the system at various points to determine where the noise is being inserted into the system. When the location of entry of the noise is found, the cause should be easily found.

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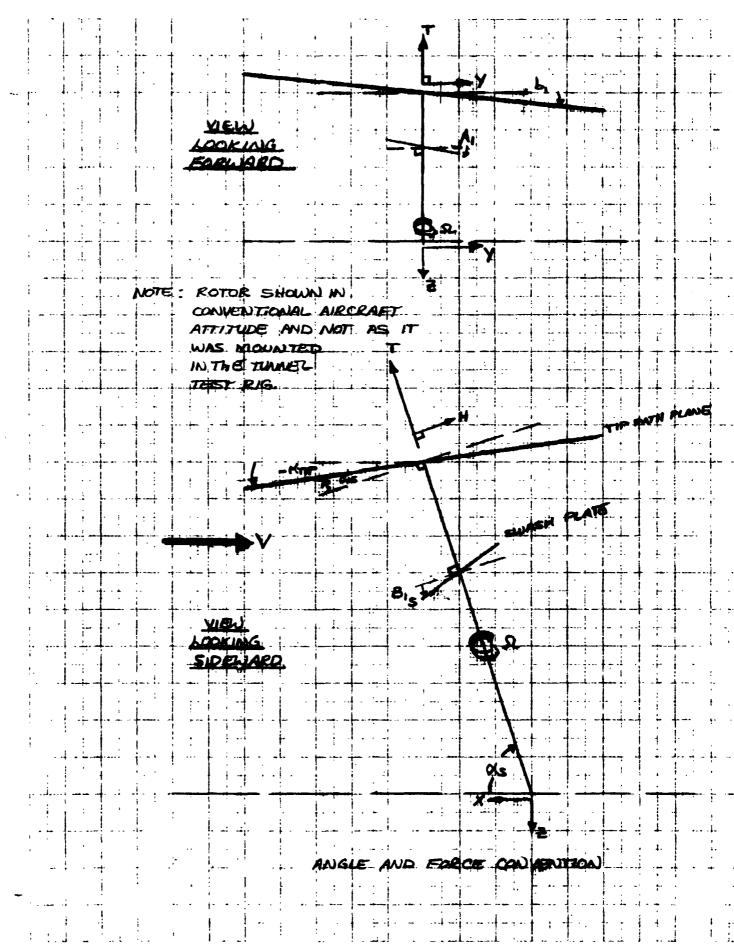
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